

Functional integral methods

①

Fokker-Planck gives us $P(x, t)$.

But what if we want to know the probability of a whole trajectory $P[X(t)]$?

$$\dot{X} = f(x) + \mathcal{J}(t)$$

We know $P[\mathcal{J}]$, want to know $P[X]$!

Simple example: Suppose we have a stochastic variable X with probability density $P_x(X)$, and $Y = f(X)$.

What is $P_y(Y)$? $P_x(X) dx = P_y(Y) dy$!

$$P_y(Y) = \int dx P_x(X) \delta(Y - f(X)) = \{ \text{change integration variable} \} = \\ = \int dy \frac{dx}{dy} P_x(X(Y)) \delta(Y - f(X)) = P_x(f^{-1}(Y)) \frac{dx}{dy}. \text{ Now generalize!}$$

$P[\mathcal{J}]$? \mathcal{J} Gaussian white noise: But $\langle \mathcal{J}^2(t) \rangle = 2B \delta(0)$ undefined!

Obtain $P[\mathcal{J}]$ as the continuum limit of a discrete process:

$$P(\mathcal{J}_i) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{\mathcal{J}_i^2}{2\sigma^2}}$$

$$P(\mathcal{J}_1, \mathcal{J}_2, \dots, \mathcal{J}_N) = \prod_{i=1}^N P(\mathcal{J}_i) \sim e^{-\frac{1}{2\sigma^2} \sum_{i=1}^N \mathcal{J}_i^2 \frac{\Delta t}{\Delta t}}$$

Take limit $\Delta t \rightarrow 0$, $N \rightarrow \infty$, $N \Delta t = t$, $\sigma^2 \Delta t = \text{const} = 2D$

$$\Rightarrow P[\mathcal{J}(t)] \sim e^{-\frac{1}{4D} \int_0^t \mathcal{J}^2(t) dt}$$

To calculate an average of some $f[\gamma]$:

$$\langle f[\gamma] \rangle = \int f[\gamma] e^{-\frac{1}{4D} \int \dot{\gamma}^2(t) dt} [d\gamma] \quad \begin{array}{l} \text{Functional} \\ \text{integral} \end{array}$$

where $[d\gamma] = \lim_{N \rightarrow \infty} \prod_{i=1}^N \left(\frac{d\gamma_i}{\sqrt{2\pi D \Delta t}} \right)$ Path integral

Generalizing the recipe above we write

$$P[x(t)] = \int [d\gamma] e^{-\frac{1}{4D} \int \dot{\gamma}^2(t) dt} \delta[x - x_{sol}]$$

Now change variables in the $\delta[\]$ functional from x to γ :

$\delta[x - x_{sol}]$ is a solution of Langevin eq.
 δ -function
 $= \lim_{N \rightarrow \infty} \prod_{i=1}^N \delta(x_i - x_{i,sol})$

$$\delta[x - x_{sol}] = \delta[\dot{x} - f(x) - \gamma(t)] J(x)$$

The δ -functional enforces x to solve the Langevin eq.

$J(x)$ = the Jacobian of the transformation

$$= \left| \frac{\delta(\dot{x} - f(x) - \gamma(t))}{\delta(x(t'))} \right| = |\det(\partial_t - f'(x))|$$

More about this later

$$P[x(t)] = \int [d\gamma] e^{-\frac{1}{4D} \int \dot{\gamma}^2(t) dt} \delta[\dot{x} - f(x) - \gamma(t)] J(x) = C e^{-\frac{1}{4D} \int (\dot{x} - f(x))^2 dt} J(x) = C e^{-S[x]} J(x)$$

S = Onsager-Machlup functional

Can use this to calculate averages, e.g.,

$$\langle x(t_1) x(t_2) \dots x(t_n) \rangle = \int [dx] e^{-S[x]} x(t_1) \dots x(t_n) J[x]$$

Define a generating functional

$$Z[\eta] = \int [dx] e^{-S + \int \eta(t) x(t) dt} J[x]$$

We now have a formulation of the problem which resembles the Feynman path integral in quantum mechanics. Can use the full machinery of quantum field theory.

Alternative form:

Use the generalizations of $\delta(x) = \int_{-\infty}^{\infty} d\tilde{x} e^{i\tilde{x}x}$

$$\text{and } \int_{-\infty}^{\infty} e^{-\frac{a}{2}x^2 + ibx} dx = \sqrt{\frac{2\pi}{a}} e^{-\frac{1}{2a}b^2}$$

$$P[x] = \int [d\tilde{x}] [d\tilde{y}] e^{-\frac{1}{4D} \int \tilde{y}^2(t) dt + i \int \tilde{x}(t) (\dot{x} - f(x) - \tilde{y}(t)) dt} J[x]$$

$$= \int [d\tilde{x}] e^{-\int D\tilde{x}^2 - i\tilde{x}(\dot{x} - f(x)) dt} J[x]$$

Carrying out the $[d\tilde{x}]$ integral gives back the first form

Compare these with the Feynman path integral

$$\begin{aligned} \int [dx] e^{iS} &= \int [dx] e^{i \int \left(\frac{m\dot{x}^2}{2} - U(x) \right) dt} \\ &= \int [dx][dp] e^{i \int \left(p\dot{x} - \frac{p^2}{2m} - U \right) dt} \end{aligned}$$

What about the Jacobian?

$$J(x) = |\det(\partial_t - f')|$$

The value depends on how the Langevin equation is discretized.

$$\dot{x} = f(x) + \mathcal{J}$$

Ito : $\frac{x(t+\tau) - x(t)}{\tau} = f(x(t)) + \mathcal{J}_t$

Stratonovich : $\frac{x(t+\tau) - x(t)}{\tau} = \frac{f(x(t+\tau)) + f(x(t))}{2} + \mathcal{J}_t$

Both are ok if used consistently.

Ito:

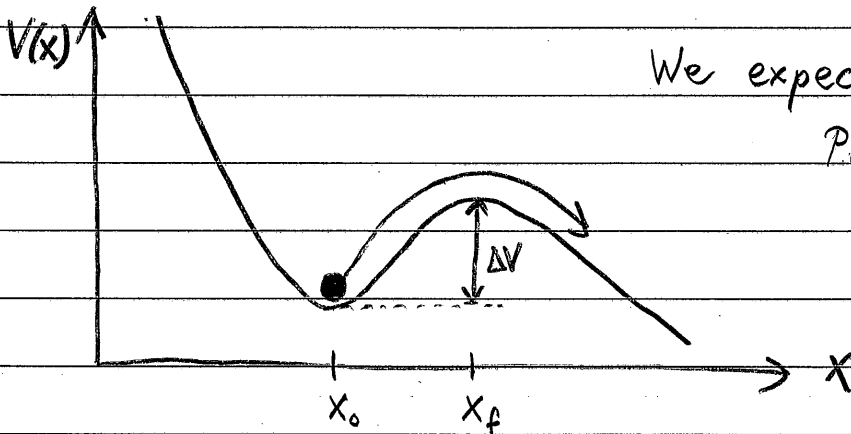
$$J(x) = \begin{vmatrix} \frac{1}{\tau} - f' - \frac{1}{\tau} & 0 & \dots \\ 0 & \frac{1}{\tau} - f' - \frac{1}{\tau} & \\ \vdots & \vdots & \ddots \end{vmatrix} = \frac{1}{\tau^N} = \text{unimportant constant!}$$

Stratonovich: $J(x) = \begin{vmatrix} \frac{1}{\tau} - \frac{1}{2}f' & -\frac{1}{\tau} - \frac{1}{2}f' \\ 0 & \dots \end{vmatrix}$

$$= \prod_{i=1}^N \left(\frac{1}{\tau} - \frac{1}{2}f' \right) = \frac{1}{\tau^N} e^{-\int \frac{1}{2} f' dt} \rightarrow \frac{1}{\tau^N} e^{-\int \frac{1}{2} f' dt}$$

Ex Escape from a potential well

Consider a Brownian particle trapped in a local minimum. What is the escape time?



We expect Arrhenius law

$$\text{Prob}(\text{escape}) \sim e^{-\frac{\Delta V}{kT}}$$

Strong friction limit \Rightarrow overdamped dynamics

$$\gamma \dot{x} = F(x) + R(t), \quad F = -\nabla V = -V'(x)$$

$$\dot{x} = \Gamma F(x) + J(t), \quad \langle J(t)J(t') \rangle = 2D \delta(t-t')$$

$$D = \Gamma kT, \quad \Gamma = 1/\gamma$$

"Action"

$$S = \int dt \frac{1}{4D} (\dot{x} - \Gamma F(x))^2$$

$$P[x(t)] [dx] = e^{-S[x]} [dx] = \text{Prob of path } x(t)$$

$$\text{Prob of escape} = P(x_f, t | x_0, t_0) =$$

$$= \int_{x(t_0)=x_0}^{x(t_f)=x_f} [dx] e^{-S[x]}$$

In general a very difficult integral!

We will use a saddle point approximation:

$$S[x] \approx S[x_{cl}] + \frac{1}{2} \iint dt dt' \delta x(t) A(t, t') \delta x(t') + \dots$$

x_{cl} minimizes S and $\delta x = x - x_{cl}$

$$P(x_f, t_f | x_0, t_0) \approx \underbrace{e^{-S[x_{cl}]}}_{\text{main contribution}} \underbrace{\int [d\delta x] e^{-\frac{1}{2} \int \delta x A \delta x}}_{\text{ignore for now}}$$

We expect this approximation to be fine when fluctuations are relatively small, i.e., at low T .

Minimize S :

$$S = \int \frac{1}{4D} (\dot{x}^2 + \Gamma^2 F^2 - 2\Gamma F \dot{x}) dt$$

Start with last term: $-\int_{t_0}^{t_f} \Gamma F(x) \dot{x} dt = \frac{\Gamma}{2D} \int_{t_0}^{t_f} \frac{dV}{dx} \frac{dx}{dt} dt =$

$$= \left\{ D = \Gamma kT \right\} = \frac{1}{2kT} (V(x_f) - V(x_0)) = \frac{\Delta V}{2kT}$$

$$\delta S_0 = \delta \int \frac{1}{4D} (\dot{x}^2 + \Gamma^2 F^2) = 0 =$$

$$= \int \frac{1}{2D} (\dot{x} \delta \dot{x} + \Gamma^2 F F' \delta x) = \int \frac{1}{2D} (-\ddot{x} + \Gamma^2 F F') \delta x$$

partial int. \uparrow $\underbrace{\hspace{10em}}_{=0}$

$$\ddot{x} = \Gamma^2 F F' \quad \text{Euler-Lagrange eq.}$$

Multiply by $\dot{x} \Rightarrow$

$$\Rightarrow \ddot{x} \dot{x} = \Gamma^2 F(x) \frac{dF}{dx} \dot{x}$$

$$\frac{d}{dt} \left(\frac{\dot{x}^2}{2} \right) = \Gamma^2 \frac{d}{dt} (F^2)$$

$$\dot{x}^2 = \Gamma^2 F^2 + C \quad \leftarrow \text{Fix using boundary conditions}$$

Assume we start at the minimum of the potential $V(x)$

$$\Rightarrow F(x_0) = 0 \quad \text{with zero velocity} \quad \dot{x}(t_0) = 0 \Rightarrow C = 0$$

$$\Rightarrow \dot{x} = \pm \Gamma F$$

Which sign should we choose?

We want to go from the minimum to the maximum, i.e., against the force \Rightarrow Choose $-$!

$$S_0 = \int dt \frac{1}{4D} (\dot{x}^2 + \Gamma^2 F^2) = \int \frac{1}{2D} (\dot{x}^2) dt =$$

$$= \int_{t_0}^{t_A} \frac{1}{2D} \left(\frac{-}{(+)} \Gamma F \right) \dot{x} = \int \frac{\Gamma}{2D} \left(\frac{+}{(-)} \frac{dV}{dx} \right) \dot{x} dt = + \frac{\Delta V}{(-) 2kT}$$

$$S_{tot} = \frac{\Delta V}{2kT (-)} + \frac{\Delta V}{2kT} = \frac{\Delta V}{kT}$$

$$\Rightarrow \text{Arrhenius law: Escape rate} \sim e^{-\frac{\Delta V}{kT}}$$

Note: There may be simpler ways to get this!?